

Leading the Future of Drive Technology

Delta Electronics, a leading brand in drive technology, has officially launched its most cost-effective classical field oriented control in AC motor drive VFD-C2000 series. This series offers four competitive values"high efficiency, high performance, lost cost of maintenance and long product life" to customers to enhance their competitive advantage while spending less cost.

Standard Models (IP20/NEMA1)

Power range: 230V 0.75~90kW, 460V 0.75~355kW

230V (kW) 0.75 1.5 2.2 3.7 5.5 7.5 11 15 18.5 22 30 37 45 55 75 90 230V (HP) 1 2 3 5 7.5 10 15 20 25 30 40 50 60 75 100 125 Frame Size A B C D E F	460V (kW)	0.75	1.5	2.2	3.7	4.0	5.5	7.5	11	15	18.5	22	30	37	45	55	75	
230V (HP) 1 2 3 5 7.5 10 15 20 25 30 40 50 60 75 100 125					2.7	4.0		7.5	11		10 E			27		E E	•	
230V (kW) 0.75 1.5 2.2 3.7 5.5 7.5 11 15 18.5 22 30 37 45 55 75 90	` '		2	3	5	7.5		15	20		30			60	-	100		
	230V (kW)	0.75	1.5	2.2	3.7	5.5	7.5	11	15	18.5	22	30	37	45	55	75	90	

Main Functions and Features

- Field oriented control with built-in PLC function
- Wide variety of applications

90 110 132 160 185 220 280 315 355 125 150 175 215 250 300 375 425 475

- Modular design for easy maintenance and many extensions
- Built-in MODBUS communication
- Long-life design and self diagnosis
- Enhanced protections and adaptation to ambient conditions
- Complies with global safety standards, including CE, UL and cUL
- Wide range of models to meet requirements
- High-speed communication interface (optional cards for PROFIBUS-DP, DeviceNet, MODBUS TCP and EtherNet/IP)
- Fully CANopen master and slave functions prepared, only option converter card CMC-COP01 needed.

High-performance Variable-frequency Technology

- 1. High bandwidth control
- 2. Speed/torque/position control mode
- 3. Dual rating design (Normal duty/heavy duty)
- 4. 4-quadrant torque control and limit
- 5. A drive for induction motor and synchronous motor

Versatile Driving Controls

- 1. Built-in safe stop function
- 2. Built-in PLC function
- 3. Built-in brake unit
- 4. Support various network protocols
- 5. Synchronous position control

Modular Design

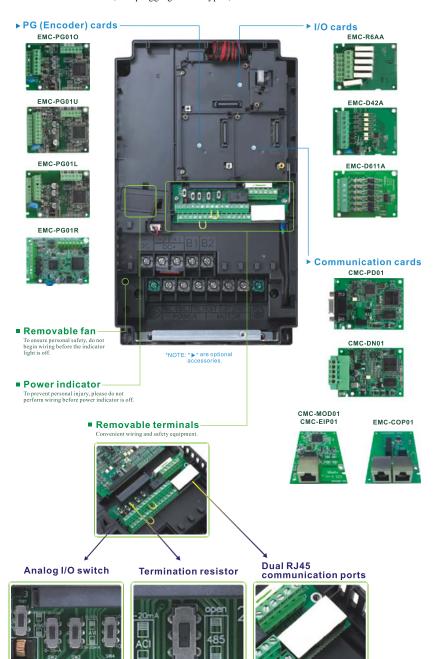
- 1. Hot-plugging digital keypad
- 2. I/O extension cards
- 3. Various PG (encoder) feedback cards
- 4. Network cards for fieldbus modules
- 5. Removable fan

Environmental Adaptability

- 1. 50°C operating temperature
- 2. Built-in DC reactor
- 3. Coated circuit boards
- 4. Built-in RFI filter
- 5. Global safety standards (CE/UL/cUL)

Modular Design

■ Various accessories options, such as I/O extension cards, encoder feedback cards, communication cards, hot-plugging LCM keypad, removable terminals and removable fan.



■ The modular design fufills the needs of system applications and equipment maintenance.



Environmental Adaptability Design

- The built-in DC reactor and RFI filter controls harmonics and noise interference effectively.
- Strong coating to ensure safe operation in harsh environments
- Heatsink and electronics components are completely isolated from each other. With the following two heatsink designs, the best cooling according to requirements is achieved:
 - (1) Flange mounting: Heat from the drive can be dissipated out of the cabinet
 - (2) Forced fan cooling: Blow cool air into aluminum heatsink.



High-speed Network Building

- Provides various communication network cards and fieldbus cards
- Advanced network functions
- Built-in RS-485 modbus protocol



 TAP-CN03 distribution box for long distances

■ CAN○○○∩ (DS402)

- Supports all Delta industrial automation products
 (all EDS files of Delta industrial automation products are built-in)
- I/O data layout of each pieces of equipments on the CANopen Network
- · Planning function for motion control







Delta DeviceNet Builder software is specially designed for DeviceNet communication. With this software, it is easy to plan DeviceNet equipment and remote I/O via parameters to build a standard DeviceNet monitoring structure.

- · Supports all Delta industrial automation products (all EDS files of Delta industrial automation products are built-in)
- I/O data layout of each piece of equipment in the DeviceNet network
- DeviceNet layout software





■ MODBUS TCP

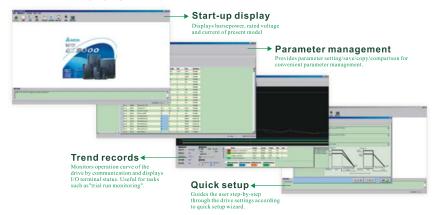
Delta's communication integrator software not only provides graphic module setting and human interface design but also supports settings and online monitoring for all Ethernet products

- Delta software for Ethernet/MODBUS TCP products
- Graphic module setting and human interface design
- · Auto search function
- · Setting interface for virtual COM port



Convenient Operation Platform for Drive System Management

■ Provides a complete operation platform for users' easy control and monitoring via PC, including parameters save/setting, real-time wave monitor, quick setup, for multiple languages and with multi-language operation systems.



Enhanced Motor Efficiency in General Applications

Improved sensorless vector control (SVC) response and torque control in, for example, crane applications.



Safe Stop Function

VFD-C2000 series is built according to category safe stop standard: EN954-1, EN60204-1 and IEC6158 to prevent personal injury at accidental start-up.

Emergency stop switch



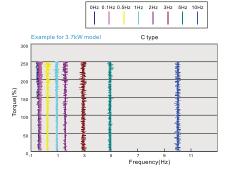
High-performance Field Oriented Control

A best choice for precise position and speed control, applicable to e.g. control printing machine.



High-performance Field Oriented Control

In FOC+PG mode, C2000 is capable of creating a start-up torque up to 200% at extremely low speed to result a much stable speed control.

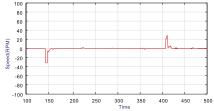


Improved Load Impact

When load changes, VFD-C2000 will provide a best torque response by FOC to minimize the vibration of load impact.

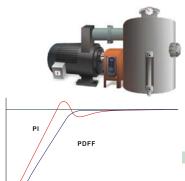


Press machine



Innovative PID Technology

Apart from traditional PI control, VFD-C2000 also provides PDFF control in speed regulation to eliminate overshoot and increase response time.



Intelligent Programmable Logic Controller

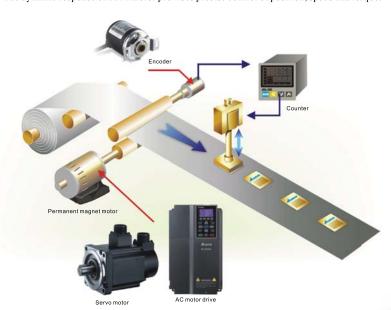
■ In network systems, distributed control and independent operation can easily be achieved with the built-in Delta PLC.



A Drive for Permanent Magnet (PM) Motors

■ VFD-C2000 is a dual mode drive for induction motors and permanent magnet motors.

The dynamic response of a PM motor provides precise control of position, speed and torque.



Environment for Operation, Storage and Transportation

				nt, such as dust, direct sunlight, corrosive/ inflammable
	Installation location	IEC60364-1/I	EC60664-1 Pollution de	gree 2,Indoor use only
	Surrounding	Storage/ Tra	nsportation	-25°C ~ +70°C
	Temperature	No-condens	ation, non-frozen	
		Operation		Max. 90%
	Rated Humidity	Storage/ Tra	nsportation	Max. 95%
		No condense	water	
	Air Pressure	Operation/ S	torage	86 to 106 kPa
	All Flessule	Transportati	on	70 to 106 kPa
핕		IEC60721-3-	3	
۱ã۱		Operation		Class 3C2 ; Class 3S2
5	Pollution Level	Storage		Class 2C2 : Class 2S2
Environment		Transportati	on	Class 1C2 : Class 1S2
🛅		No concentr	ate	
	Altitude	Operation	If it is install at altitude	stalled at altitude 0~1000m, follow normal operation restriction. e 1000~3000m, decrease 2% of rated current or lower 0.5°C of ry 100m increase in altitude. Maximum altitude for Corner
	Package Drop	Storage/ Tra	nsportation	ISTA procedure 1A(according to weight) IEC60068-2-31
	Vibration		to peak value range from om 55Hz to 512 Hz. Com	ı 2Hz to 13.2 Hz; 0.7G∼1.0G range from 13.2Hz to 55Hz; ply with IEC 60068-2-6
	Impact	IEC/EN 60068	3-2-27	
	Operation Position		offset angle ± 10° I installation position)	10 [*]

Specification for Operation Temperature and Protection Level

	Model	Frame	Top cover	Conduit Box	Protection Level	Operation Temperature
Ì		Frame A~C 230V: 0.75~22kW	Remove top cover	Standard	IP20/UL Open Type	-10°C ~50°C
		460V: 0.75~30kW	Standard with top cover	conduit plate	IP20/UL Type1/NEMA1	-10°C ~40°C
	VFDxxxCxxA	Frame D~H 230V: >22kW 460V: >30kW	N/A	No conduit box	IP00 IP20/UL Open Type Only the circled area is IP00, others are IP20.	-10°C ~50°C
		Frame A~C	Remove top cover	Standard	IP20/UL Open Type	-10°C ~50°C
		460V: 0.75~30kW	Standard with top cover	conduit plate	IP20/UL Type1/NEMA1	-10°C ~40°C
	VFDxxxCxxE	Frame D~H 230V: >22kW 460V: >30kW	N/A	Standard conduit box	IP20/UL Type1/NEMA1	-10°C ~40°C

Specifications

23	ov	Frame Size		F	4			В			С)		Е		F
20		Model VFDC	007	015	022	037	055	075	110	150	185	220	300	370	450	550	750	900
		Applicable Motor Output (kW)	0.75	1.5	2.2	3.7	5.5	7.5	11	15	18.5	22	30	37	45	55	75	90
		Applicable Motor Output (hp)	1	2	3	5	7.5	10	15	20	25	30	40	50	60	75	100	125
	ξ	Rated Output Capacity (kVA)	1.9	2.8	4.0	6.4	9.6	12	19	25	28	34	45	55	68	81	96	131
Ę.	HEAVY DUTY	Rated Output Current (A)	4.8	7.1	10	16	24	31	47	62	71	86	114	139	171	204	242	329
Ratir	뿐	Carrier Frequency (kHz)								2~6	kHz							
Output Rating	ΛTΩ	Rated Output Capacity (kVA)	2.0	3.2	4.4	6.8	10	13	20	26	30	36	48	58	72	86	102	138
0	NORMAL DUTY	Rated Output Current (A)	5	8	11	17	25	33	49	65	75	90	120	146	180	215	255	346
	N	Carrier Frequency (kHz)			2	~15kH	z				2	~10kH	lz			2~9	kHz	
βι		Input Current (A) Heavy Duty	6.1	11	15	18.5	26	34	50	68	78	95	118	136	162	196	233	315
Input Rating		Input Current (A) Normal Duty	6.4	12	16	20	28	36	52	72	83	99	124	143	171	206	245	331
Indu		Rated Voltage/ Frequency					3-ph	ase A C	200V	~240V	(-15%	~+10%	6), 50/	60Hz				
		Operating Voltage Range								170~2	65Vac							
		Frequency Tolerance								47~6	63Hz							
		Cooling Method	Natural cooling							Fanc	ooling							
		Braking Chopper					Built	t-in							Op	ion		
		DC Reactor					Opti	ion							Bui	lt-in		
		EMI Filter								Op	tion							

46	ov	Frame Size			1	4				В			С	
40	UV	Model VFDC	007	015	022	037	040	055	075	110	150	185	220	300
		Applicable Motor Output (kW)	0.75	1.5	2.2	3.7	4.0	5.5	7.5	11	15	18.5	22	30
		Applicable Motor Output (hp)	1	2	3	5	5	7.5	10	15	20	25	30	40
5	HEAVY DUTY	Rated Output Capacity (kVA)	2.3	3.0	4.5	6.5	7.6	9.6	14	18	24	29	34	45
뜵	₹	Rated Output Current (A)	2.9	3.8	5.7	8.1	9.5	11	17	23	30	36	43	57
æ	뿦	Carrier Frequency (kHz)						2~6	kHz					
Output Rating	NORMAL DUTY	Rated Output Capacity (kVA)	2.4	3.2	4.8	7.2	8.4	10	14	19	25	30	36	48
0	3MA	Rated Output Current (A)	3.0	4.0	6.0	9.0	10.5	12	18	24	32	38	45	60
	Š	Carrier Frequency (kHz)				:	2~15kH:	z				2	2~10kH	Z
gı		Input Current (A) Heavy Duty	4.1	5.6	8.3	13	14.5	16	19	25	33	38	45	60
Input Rating		Input Current (A) Normal Duty	4.3	5.9	8.7	14	15.5	17	20	26	35	40	47	63
E E		Rated Voltage/Frequency			3	-phase	AC 380\	/~480V	(-15%~	+10%),	50/60H	z		
트		Operating Voltage Range						323~5	28Vac					
		Frequency Tolerance						47~6	3Hz					
		Cooling Method	Natural	cooling					Fanc	ooling				
		Braking Chopper						Bui	lt-in					
		DC Reactor						Op	tion					
		EMI Filter					/FDXXX							

- NOTE:

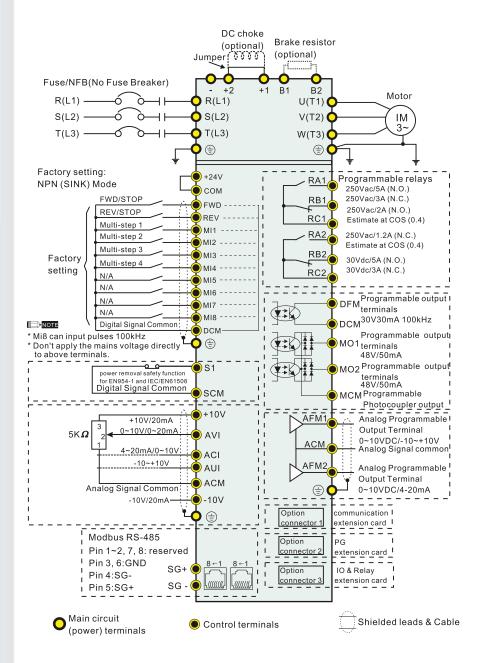
 ' Frame F-H is under development.
 For FRAME A, B and C, Model VFDXXXC43A is under IP20/NEMA1/UL TYPE1 protection level.
 For FRAME D and above, if the last character of the model is A then it is under IP20 protection level but the wiring terminal is under IP00 protection level; if the last character of the model is E, it is under IP20/NEMA1/UL TYPE1 protection level.

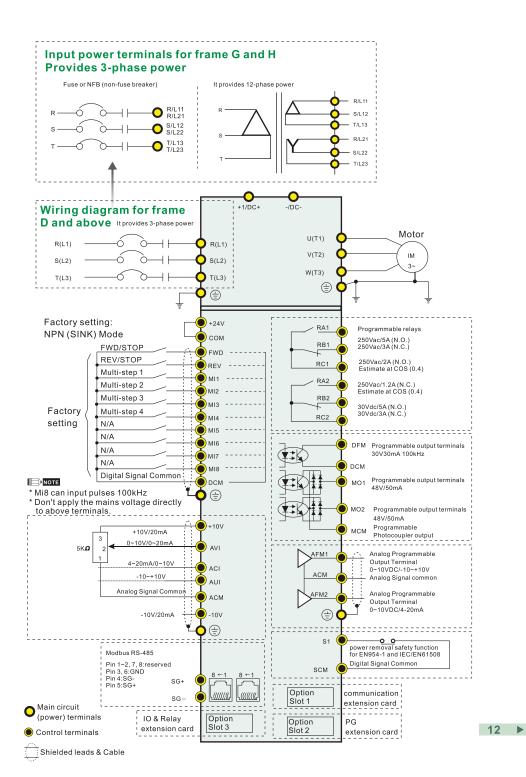
46	ov	Frame Size		[)		E	Ξ	*	F	*	G		*H	
70		Model VFDC	370	450	550	750	900	1100	1320	1600	1850	2200	2800	3150	3550
		Applicable Motor Output (kW)	37	45	55	75	90	110	132	160	185	220	280	315	355
		Applicable Motor Output (hp)	50	60	75	100	125	150	175	215	250	300	375	425	475
5	НЕАVY DUTY	Rated Output Capacity (kVA)	55	69	84	114	136	167	197	235	280	348	417	466	517
뱵	Ş	Rated Output Current (A)	69	86	105	143	171	209	247	295	352	437	523	585	649
æ	뿐	Carrier Frequency (kHz)							2~6kHz						
Output Rating	NORMAL DUTY	Rated Output Capacity (kVA)	58	73	88	120	143	175	207	247	295	367	438	491	544
0	SMA.	Rated Output Current (A)	73	91	110	150	180	220	260	310	370	460	550	616	683
	<u>S</u>	Carrier Frequency (kHz)		2~10)kHz						2~9kHz				
5		Input Current (A) Heavy Duty	70	96	108	149	159	197	228	285	361	380	469	527	594
Input Rating		Input Current (A) Normal Duty	74	101	114	157	167	207	240	300	380	400	494	555	625
P I		Rated Voltage/Frequency				3-ph	aseAC	380V~4	80V (-1	5%~+10	%),50/	60Hz			
드		Operating Voltage Range						32	3~528V	ac					
		Frequency Tolerance						4	47~63H:	Z					
		Cooling Method						F	an cooli	ng					
		Braking Chopper							Option						
		DC Reactor							Built-in						
		EMI Filter							3A: with 3E: built						

Control Method	4.WE 2.0VO 2.VE.DO 4.F00.DO 5.T00.DO
	1: V/F, 2: SVC, 3: VF+PG, 4: FOC+PG, 5: TQC+PG,
Starting Torque	Reach up to 150% or above at 0.5Hz. Under FOC+PG mode, starting torque can reach 150% at 0Hz.
V/f Curve	4-point adjustable V/f curve and square curve
Speed Response Ability	5Hz (vector control can reach up to 40Hz)
Torque Limit	Max. 200% torque current
Torque Accuracy	±5%
Max. Output Frequency (Hz)	Normal duty: 0.01~600.00Hz; Heavy duty: 0.00 ~ 300.00 Hz
Frequency Output Accuracy	Digital command: ±0.01%, -10°C ~+40°C, Analog command: ±0.1%, 25±10°C
Output Frequency Resolution	Digital command: 0.01Hz · Analog command: 0.03 X max. output frequency/60 Hz (±11 bit)
Overload Tolerance	Normal duty: rated output current is 120% for 60seconds Heavy duty: rated output current is 150% for 60seconds
Frequency Setting Signal	+10V~-10,0~+10V,4~20mA,0~20mA,Pulse input
Accel./decel. Time	0.00~600.00/0.0~6000.0 Seconds
Main Control Function	Torque control, Droop control, Speed/torque control switching, Feed forward control, Zero-servo control, Momentary power loss ride thru, Speed search, Over-torque detection, Torque limit. 17-step speed (max), Accel/decel time switch, S-curve accel/decel, 3-wire sequence knuto-Tuning (rotational, stationary), Dwell, Cooling fan on/off switch, Slip compensation, Torque compensation JOG frequency, Frequency upper/lower limit settings, DC injection braking at start/stop, High slip braking, PID control (with sleep function), Energy saving control, MODOBUS communication (RS-485 RJ45, max. 115.2 kbps), Fault restart, Parameter copy
Fan Control	230V model: VFD150C23A(include) and series above: PMW control; VFD150C23A and series below: on/off switch control 460V model: VFD150C23A(include) and series above: PMW control; VFD150C23A and series below: on/off switch control
Motor Protection	Electronic thermal relay protection
Over-current Protection	Over-current protection for 220% rated current current clamp F Normal duty: around 170~175% $_{\rm d}$: F Heavy duty: around 180~185% $_{\rm d}$
Over-voltage Protection	230: drive will stop when DC-BUS voltage exceeds 410V 460: drive will stop when DC-BUS voltage exceeds 820V
Over-temperature Protection	Built-in temperature sensor
Stall Prevention	Stall prevention during acceleration, deceleration and running independently.
Restart after Instantaneous Power Failure	Parameter setting up to 20 seconds
Grounding Leakage Current Protection	Leakage current is higher than 50% of rated current of the AC motor drive

Wiring

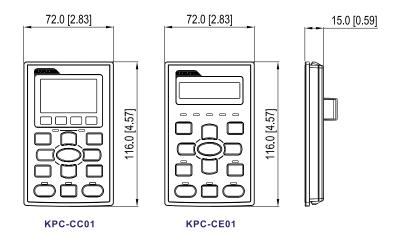
Frame A~C Offers 3-phase power supply





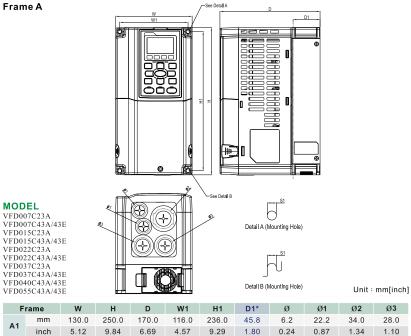
Dimensions

■ Digital Keypad



Frame A

inch



 $NOTE: Model\ VFD007C43E; VFD015C43E; VFD022C43E; VFD037C43E; VFD040C43E; VFD055C43E\ will be\ available\ for\ ordering\ soon.$ Please contact your local distributor or Delta representative for detailed launch schedule.

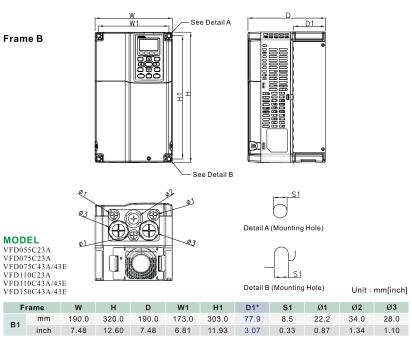
9.29

0.24

0.87

1.34

Frame B



NOTE: Model VFD075C43E; VFD110C43E; VFD150C43E will be available for ordering soon. Please contact your local distributor or Delta representative for detailed launch schedule

Frame C

MODEL

VFD150C23A

VFD185C23A

VFD220C23A

VFD185C43A/43E

VFD220C43A/43E

VFD300C43A/43E

Frame

C1

mm

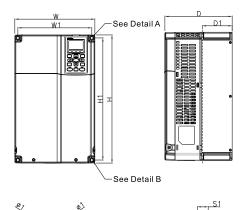
inch

В1

MODEL VFD055C23A VFD075C23A

VFD110C23A

Frame



Detail A (Mounting Hole)

Detail B (Mounting Hole)

D W1 H1 D1* S1 Ø2 Ø3 250.0 400.0 210.0 231.0 381.0 92.9 34.0 50.0 8.5 22.2 9.84 15.75 8.27 9.09 15.00 3.66 0.33 0.87 1.34 1.97

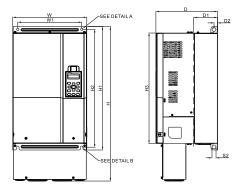
NOTE: Mode VFD185C43E; VFD220C43E; VFD300C43E will be available for ordering soon. Please contact your local distributor or Delta representative for detailed launch schedule.

Unit : mm[inch]

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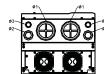
Dimensions

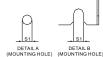
Frame D



MODEL

FRAME_D1 FRAME_D2
VFD300C23A VFD370C23E
VFD370C43A VFD370C43A
VFD370C43A VFD370C43E
VFD550C43A VFD550C43E
VFD750C43A VFD750C43E

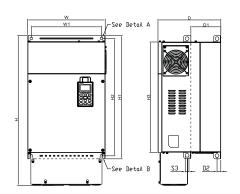




,	,,	Unit :	mm[inch]
		0	[

F	rame	W	Н	D	W1	H1	H2	Н3	D1*	D2	S1	S2	Ø1	Ø2	Ø3
	D1	330.0 [12.99]	-					492.0 [19.37]					-	-	-
	D2	330.0 [12.99]						492.0 [19.37]							22.0 [0.87]

Frame E



MODEL

 FRAME_E1
 FRAME_E2

 VFD450C23A
 VFD450C23E

 VFD550C23A
 VFD550C23E

 VFD750C23A
 VFD750C23E

 VFD900C43A
 VFD900C43E

 VFD1100C43A
 VFD1100C43E



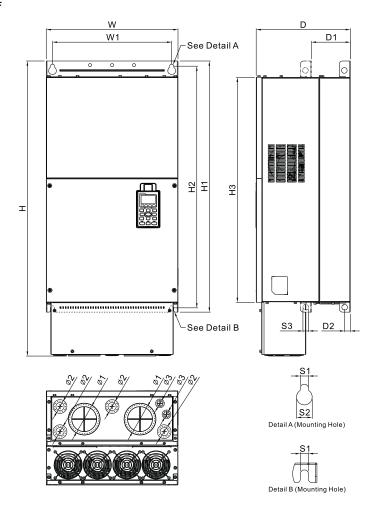




Unit : mm[inch]

Frame	W	Н	D	W1	H1	H2	Н3	D1*	D2	S1,S2	S3	Ø1	Ø2	Ø3
E1	370.0 [14.57]	-		335.0 [13.19]		560.0 [22.05]	528.0 [20.80]					-	-	-
E2	370.0 [14.57]	715.8 [28.18]	300.0 [11.81]	335.0 [13.19]	589 [23.19]	560.0 [22.05]	528.0 [20.80]	143.0 [5.63]	18.0 [0.71]	13.0 [0.51]	18.0 [0.71]	22.0 [0.87]	34.0 [1.34]	92.0 [3.62]

■ Frame F



MODEL

FRAME_F1 VFD900C23A VFD1320C23A VFD1600C23A FRAME_F2 VFD900C23E VFD1320C43E VFD1600C43E

Frame	W	Н	D	W1
F1	420.0 [16.54]	-	300.0 [11.81]	380.0 [14.96]
F2	420.0 [16.54]	940.0 [37.00]	300.0 [11.81]	380.0 [14.96]

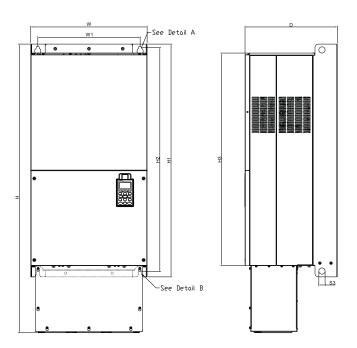
Unit : mm[inch]

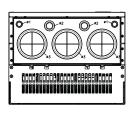
Frame	H1	H2	Н3	D1*	D2	S1	S2	S3	Ø1	Ø2	Ø3
F1	800.0	770.0	717.0	124.0	18.0	13.0	25.0	18.0	92.0	35.0	22.0
	[31.50]	[30.32]	[28.23]	[4.88]	[0.71]	[0.51]	[0.98]	[0.71]	[3.62]	[1.38]	[0.87]
F2	800.0	770.0	717.0	124.0	18.0	13.0	25.0	18.0	92.0	35.0	22.0
	[31.50]	[30.32]	[28.23]	[4.88]	[0.71]	[0.51]	[0.98]	[0.71]	[3.62]	[1.38]	[0.87]

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Dimensions

Frame G









Detail A (Mounting Hole)

Detail B (Mounting Hole)

MODEL

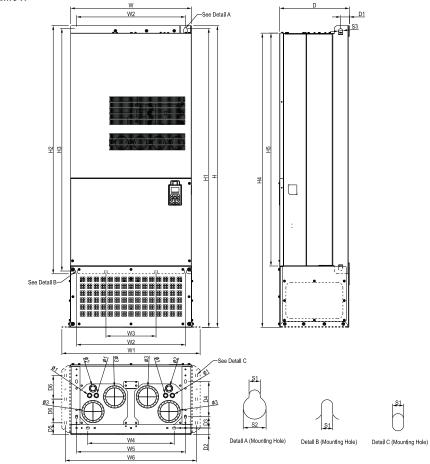
FRAME_G1 FRAME G2 VFD1850C43A VFD1850C43E VFD2200C43A VFD2200C43E

Frame	W	Н	D
G1	500.0 [19.69]	-	397.0 [15.63]
G2	500.0 [19.69]	1240.2 [48.83]	397.0 [15.63]

Unit : mm[inch]

Frame	W1	H1	H2	Н3	S1	S2	S3	Ø1	Ø2	Ø3
G1	440.0 [217.32]	1000.0 [39.37]	963.0 [37.91]	913.6 [35.97]	13.0 [0.51]	26.5 [1.04]	27.0 [1.06]	-	-	-
G2	440.0 [217.32]	1000.0	963.0 [37.91]	913.6	13.0 [0.51]	26.5 [1.04]	27.0 [1.06]	22.0 [0.87]	34.0 [1.34]	117.5 [4.63]

Frame H



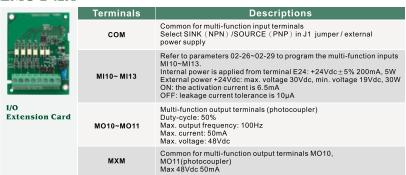
MODEL FRAME_H1 FRAME_H2 VFD2800C43E-1 FRAME_H3 VFD2800C43A VFD2800C43E VFD3150C43E-1 VFD3150C43E VFD3150C43A VFD3550C43A VFD3550C43E-1 VFD3550C43E

Unit : mm[inch]

Frame	W	Н	D	W1	W2	W3	W4	W5	W6	H1	H2	Н3	H4
Н1	700.0 [27.56]	-	398.0 [15.67]	-	630.0 [24.80]	290.0 [11.42]	-	-	-	-	1435.0 [56.50]	1403.0 [55.24]	-
H2	700.0 [27.56]	1745.0 [68.70]	404.0 [15.91]	800.0 [31.50]	-	-	500.0 [19.69]	630.0 [24.80]	760.0 [29.92]	1729.0 [68.07]	-	-	1701.6 [66.99]
Н3	700.0 [27.56]	1745.0 [68.70]	404.0 [15.91]	800.0 [31.50]	-	-	500.0 [19.69]	630.0 [24.80]	760.0 [29.92]	1729.0 [68.07]	-	-	1701.6 [66.99]
Frame	H5	D1	D2	D3	D4	D5	D6	S1	S2	S3	Ø1	Ø2	Ø3
Н1	1346.6 [53.02]	45.0 [1.77]	-	-	-	-	-	13.0 [0.51]	26.5 [1.04]	25.0 [0.98]	-	-	-
H2	1346.6 [53.02]	51.0 [2.01]	38.0 [1.50]	65.0 [2.56]	204.0 [8.03]	68.0 [2.68]	137.0 [5.39]	13.0 [0.51]	26.5 [1.04]	25.0 [0.98]	-	-	-
Н3	1346.6 [53.02]	51.0 [2.01]	38.0 [1.50]	65.0 [2.56]	204.0 [8.03]	68.0 [2.68]	137.0 [5.39]	13.0 [0.51]	26.5 [1.04]	25.0 [0.98]	22.0 [0.87]	34.0 [1.34]	117.5 [4.63]

Option Cards

EMC-D42A



EMC-D611A

O MARKET THE AREA .	Terminals	Descriptions
A Laborator	AC	AC power common for multi-function input terminal (Neutral)
I/O Extension Card	MI10~ Mi15	Refer to Pr. 02.26~ Pr. 02.31 for multi-function input selection Input voltage: 100-130VAC Input frequency: 57-63Hz Input impedance: 27Kohm Terminal response time: ON: 10ms OFF: 20ms

EMC-R6AA

	Terminals	Descriptions
Relay Extension Card	R10A~R15A R10C~R15C	Refer to Pr. 02.36~ Pr. 02.41 for multi-function input selection Resistive load: 5A(N.O.)/3A(N.C.) 250VAC 5A(N.O.)/3A(N.C.) 30Vdc Inductive load (COS 0.4) 2.0A(N.O.)/1.2A(N.C.) 250VAC 2.0A(N.O.)/1.2A(N.C.) 30Vdc It is used to output each monitor signal, such as for drive in operation, frequency attained or overload indication.

EMC-PG01L

EMIC-I GUI.	ENIC I GUIL					
	Tern	ninals	Descriptions			
		VP	Output voltage for power: $+5V/+12V\pm5\%$ (use FSW3 to switch $+5V/+12V$) Max. output current: 200mA			
00 0	PG1	DCM	Common for power and signal			
		A1, /A1 B1, /B1 Z1, /Z1	Encoder Input signal It can be 1-phase or 2-phase input. Max. output frequency: 300kP/sec			
Set by Pr.10-00~10-02	PG2	A2, /A2 B2, /B2	Pulse Input signal It can be 1-phase or 2-phase input. Max. output frequency: 300kP/sec.			
	PG OUT	AO, /AO BO, /BO ZO, /ZO	PG Card Output signals. It has division frequency function: 1~255 times Max. output voltage for Line driver: 5Vdc Max. output current: 50mA Max. output current: 50mA Max. output trequency: 300kP/sec			

EMC-PG01O

The state of the s	Ter	minals	Descriptions
		VP	Output voltage for power: +5V/+12V \pm 5% (use FSW3 to switch +5V/+12V) Max. output current: 200mA
	PG1	DCM	Common for power and signal
mm j		A1, /A1 B1, /B1 Z1, /Z1	Encoder Input signal It can be 1-phase or 2-phase input. Max. output frequency: 300kP/sec
Set by Pr.10-00~10-02	PG2	A2, /A2 B2, /B2	Pulse Input Signal It can be 1-phase or 2-phase input. Max. output frequency: 300kP/sec.
		V+	Needs external power source for PG OUT circuit.
		V-	Input voltage of power:+12V ~ +24V
	PG OUT	A/O, B/O, //O	PG Card Output signals. It has division frequency function: 1~255 times Input signal of open collector. Please add a pull-high resistor on the external power V+~V-(e.g. power of PLC) to prevent the interference of the receiving signal. Max. Output current: 20mA. Max output frequency: 300KP/Sec

EMC-PG01R

	Terminals		Descriptions
	PG1	R1- R2	Resolver Output Power 7Vrms, 10kHz
	FGI	S1,S2, S3, S4,	Resolver Input Signal 3.5±0.175Vrms, 10kHz
a and a	PG2	A2, /A2 B2, /B2	Pulse Input Signal It can be 1-phase or 2-phase input. Max. output frequency: 300kP/sec.
Set by Pr.10-00~10-02	PG OUT	AO, /AO, BO /BO, ZO, /ZO	PG Card Output signals. It has division frequency function: 1~255 times Max. output voltage for Line driver: 5Vdc Max. output current: 50mA Max. output frequency: 300kP/sec

Screw Specifications for Option card Terminals:

EMC-D42A	Wire gauge	24~12AWG (0.205~3.31mm²)
EWIC-D42A	Torque	4Kg-cm [3.47lb-in]
EMC-R6AA	Wire gauge	24~16AWG (0.205~1.31mm²)
EWC-ROAA	Torque	6Kg-cm [5.21lb-in]
EMC-PG01L		
EMC-PG010	Wire gauge	30~16AWG (0.0509~1.31mm²)
EMC-PG01R	Torque	2Kg-cm [1.74lb-in]
EMC-PG01U		

Option Cards

EMC-PG01U

- FJMP1S: Standard UVW Output Encoder; D: Delta Encoder
- Set by Pr.10-00~10-02



Terminals		Descriptions
	VP	Output voltage for power: +5V/+12V5% (use FSW3 to switch +5V/+12V) Max. output current: 200mA
	DCM	Common for power and signal
PG1	A1, /A1, B1, /B1, Z1, /Z1	Encoder input signal 1-phase or 2-phase input. Max. output frequency: 300kP/sec
	U1, /U1, V1, V1, W1, /W1	Encoder input signal
PG2	A2, /A2 B2, /B2	Pulse Input signal 1-phase or 2-phase input. Max. output frequency: 300kP/sec.
PG OUT	AO, /AO, BO, /BO, ZO, /ZO	PG Card Output signals. Division frequency function: 1~255 times Max. output voltage for Line driver: 5Vdc Max. output current: 50mA Max. output frequency: 300kP/sec

CMC-MOD01



Features

- MDI/MDI-X auto-detect E-mail alarm
- Virtual serial port. Baud rate: 10/100Mbps auto-detect
- Supports Modbus TCP protocol
- AC motor drive keypad/Ethernet configuration

Network Interface

Interface	RJ-45 with Auto MDI/MDIX
Number of ports	1 Port
Transmission method	IEEE 802.3, IEEE 802.3u
Transmission cable	Category 5e shielding 100M
Transmission speed	10/100 Mbps Auto-Detect
Network protocol	ICMP, IP, TCP, UDP, DHCP, SMTP, MODBUS OVER TCP/IP, Delta Configuration

CMC-EIP01



Features

- MDI/MDI-X auto-detect Virtual serial port
- Supports Modbus TCP and Ethernet/IP protocol
- Baud rate: 10/100Mbps auto-detect
- AC motor drive keypad/Ethernet configuration

Network Interface

Interface	RJ-45 with Auto MDI/MDIX
Number of ports	1 Port
Transmission method	IEEE 802.3, IEEE 802.3u
Transmission cable	Category 5e shielding 100M
Transmission speed	10/100 Mbps Auto-Detect
Network protocol	ICMP, IP, TCP, UDP, DHCP, HTTP, SMTP, MODBUS OVER TCP/IP, EtherNet/IP, Delta Configuration

CMC-PD01



Features

- Supports PZD control data exchange.
- Supports PKW polling AC motor drive parameters.
- Supports user diagnosis function.
- Auto-detects baud rates; supports Max. 12Mbps.

PROFIBUS DP Connector

Interface	DB9 connector
Transmission method	High-speed RS-485
Transmission cable	Shielded twisted pair cable
Electrical isolation	500VDC

Communication

Message type	Cyclic data exchange
Module name	CMC-PD01
GSD document	DELA08DB.GSD
Company ID	08DB (HEX)
Serial transmission speed supported (auto-detection)	9.6kbps; 19.2kbps; 93.75kbps; 187.5kbps; 125kbps; 250kbps; 500kbps; 1.5Mbps; 3Mbps; 6Mbps; 12Mbps (bits per second)

CMC-DN01



Features

- Based on the high-speed communication interface of Delta HSSP protocol, able to conduct immediate control of AC motor drive.
- Supports Group 2 only connection and polling I/O data exchange.
- For I/O mapping, supports Max. 32 words of input and 32 words of output.
- Supports EDS file configuration in DeviceNet configuration software.
- Supports all baud rates on DeviceNet bus: 125kbps, 250kbps, 500kbps and extendable serial transmission speed mode.
- Node address and serial transmission speed can be set up on AC motor drive.
- Power supplied from AC motor drive.

DeviceNet Connector

Interface	5-PIN open removable connector. Of 5.08mm PIN interval
Transmission method	CAN
Transmission cable	Shielded twisted pair cable (with 2 power cables)
Transmission speed	125kbps, 250kbps, 500kbps and extendable serial transmission speed mode
Network protocol	DeviceNet protocol

AC Motor Drive Connection Port

Interface	50 PIN communication terminal
Transmission method	SPI communication
Terminal function	Communicating with AC motor drive Transmitting power supply from AC motor drive
Communication protocol	Delta HSSP protocol

Option Cards

EMC-COP01



RJ-45 Pin definition





Pin	Pin name	Definition
1	CAN_H	CAN_H bus line (dominant high)
2	CAN_L	CAN_L bus line (dominant low)
3	CAN_GND	Ground/0V/V-
7	CAN_GND	Ground/0V/V-

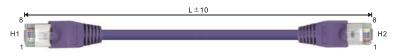
Specification

Male

Interface	RJ-45
Number of ports	1 Port
Transmission method	CAN
Transmission cable	CAN standard cable
Transmission speed	1M 500k 250k 125k 100k 50k
Communication protocol	CANopen

■ CANopen Communication Cable

Model: TAP-CB03, TAP-CB04



Title	Part No.	L		
Title		mm	inch	
1	TAP-CB03	500 ± 10	19±0.4	
2	TAP-CB04	1000±10	39 ± 0.4	

■ CANopen Dimensions

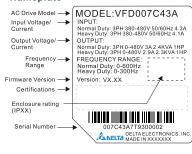
Model: TAP-CN03



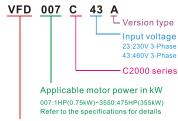
Ordering information



■ Nameplate



■ Model name



Series name(Variable Frequency Drive)

■ Optional Accessories

- ▶ Digital Keypad KPC-CE01
- ▶ Option Cards
- ▶ Fuse
- ▶ Non-fuse Circuit Breaker
- ▶ All Brake Resistors and Brake Units Used in AC Motor Drives
- AC Reactor
- ▶ Zero Phase Reactor
- ▶ DC Reactor
- ► EMI Filter
- ▶ Panel Mounting
- ► Conduit Box Kit
- ▶ Fan Kit
- ▶ Flange Mounting Kit



Attention

Standard Motors

Used with 400V Standard Motors
It is recommended to add an AC output reactor
when using with a 400V standard motor to prevent
damage to motor insulation.

· Torque Characteristics and Temperature Rise

When a standard motor is drive controlled, the motor temperature will be higher than with DOL operation.

Please reduce the motor output torque when operating at low speeds to compensate for less cooling efficiency.

For continuous constant torque at low speeds, external forced motor cooling is recommended.

· Vibration

When the motor drives the machine, resonances may occur, including machine resonances. Abnormal vibration may occur when operating a 2-pole motor at 60Hz or higher.

Noise

When a standard motor is drive controlled, the motor noise will be higher than with DOL operation. To lower the noise, please increase the carrier frequency of the drive. The motor fan can be very noisy when the motor speed exceeds 60Hz.

Special Motors

· High-speed Motor

To ensure safety, please try the frequency setting with another motor before operating the high-speed motor at 120Hz or higher.

· Explosion-proof Motor

Please use a motor and drive that comply with explosion-proof requirements.

· Submersible Motor & Pump

The rated current is higher than that of a standard motor.

Please check before operation and select the capacity of the AC motor drive carefully. The motor temperature characteristics differ from a standard motor, please set the motor thermal time constant to a lower value.

. Brake Motor

When the motor is equipped with a mechanical brake, the brake should be powered by the mains supply

Damage may occur when the brake is powered by the drive output. Please DO NOT drive the motor with the brake engaged.

· Gear Motor

In gearboxes or reduction gears, lubrication may be reduced if the motor is continuously operated at low speeds. Please DO NOT operate in this way.

· Synchronous Motor

These of motors need suitable software to control them. Please contact Delta for more information.

· Single-phase Motor

Single-phase motors are not suitable for being operated by an AC Motor Drive. Please use a 3-phase motor instead when necessary.

Environmental Conditions

Installation Position

- The drive is suitable for installation in a place with ambient temperature from -10 to 50°C.
- The surface temperature of the drive and brake resistor will rise under specific operation conditions. Therefore, please install the drive on materials that are noncombustible.
- Ensure that the installation site complies with the ambient conditions as stated in the manual.

Wiring

Limit of Wiring Distance

For the remote operation, please use twist-shielding cable and the distance between the drive and control box should be less than 20m.

· Maximum Motor Cable Length

Motor cables that are too long may cause overheating of the drive or current peaks due to stray capacitance. Please ensure that the motor cable is less than

Please ensure that the motor cable is less than 30m.

If the cable length can't be reduced, please lower the carrier frequency or use an AC reactor.

· Choose the Right Cable

Please refer to current value to choose the right cable section with enough capacity or use recommended cables.

· Groundina

Please ground the drive completely by using the grounding terminal.

How to Choose the Drive Capacity

· Standard Motor

Please select the drive according to applicable motor rated current listed in the drive specification.

Please select the next higher power AC drive in case higher starting torque or quick acceleration/deceleration is needed.

· Special Motor

Please select the drive according to: Rated current of the drive > rated current of the motor

Peripheral Equipment

Molded-Case Circuit Breakers (MCCB)

Please install the recommended MCCB or ELCB in the main circuit of the drive and make sure that the capacity of the breaker is equal to or lower than the recommended one.

Add a Magnetic Contactor(MC) in the Output Circuit

When a MC is installed in the output circuit of the drive to switch the motor to commercial power or other purposes, please make sure that the drive and motor are completely stopped and remove the surge absorbers from the MC before switching it.

Add a Magnetic Contactor (MC) in the Input Circuit

Please only switch the MC ONCE per hour or it may damage the drive. Please use RUN/STOP signal to switch many times during motor operation.

Motor Protection

The thermal protection function of the drive can be used to protect the motor by setting the operation level and motor type (standard motor or variable motor). When using a high-speed motor or a water-cooled motor the thermal time constant should be set to a lower value.

When using a longer cable to connect the motor thermal relay to a motor, high-frequency currents may enter via the stray capacitance. It may result in malfunctioning of the relay as the real current is lower than the setting of thermal relay. Under this condition, please lower the carrier frequency or add an AC reactor to solve

· DO NOT Use Capacitors to

Improve the Power Factor
Use a DC reactor to improve the power factor of
the drive. Please DO NOT install power factor
correction capacitors on the main circuit of the
drive to prevent motor faults due to over current.

· Do NOT Use Surge Absorber Please DO NOT install surge absorbers on the

Please DO NOT install surge absorbers on t output circuit of the drive.

· Lower the Noise

To ensure compliance with EMC regulations, usually a filter and shielded wiring is used to lower the noise.

Method Used to Reduce the Surge Current

Surge currents may occur in the phase-lead capacitor of the power system, causing an overvoltage when the drive is stopped or at low leads.

It is recommended to add a DC reactor to the drive.

Transportation and Storage

Please transport and store the drive in a place that meets environment specifications.

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